# TRIPL-DA: A New Opportunity at CCMC

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Jan 17, 2012



## Introduction

#### Goal

#### Specify the ionosphere completely to support iono, science and space weather:

- Structure (bubbles, sporadic E, profile shapes, auroral ovals, ...)
- Dynamics (TIDs, connection with AGWs, ...)
- Response to solar input
- Response to magnetic storms
- Daily or shorter variations (weather)
- Connections to climate science

#### Method

#### 3DVAR data assimilation:

- Prior based on realistic physics (climo model, etc.)
- Arbitrary data sources possible
- Can get time evolution with Kalman filter
- True 3D specification
- Established technique in atmospheric weather modelling
- ▶ TRIPL-DA is ARL:UT's updated 3DVAR tool.



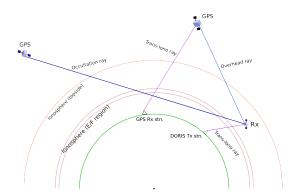
## TRIPL-DA

- Specifies only n<sub>e</sub> (not other chemical species)
- Works in  $log(n_e)$  space
  - Guarantees positive-definite specification
  - Easy to ingest multiple data types
- Ingests your favorite background model prior
- ▶ Global or regional grid
- ▶ User can specify arbitrary grid
  - Lat/Lon is independent of Alt, may be regular or irregular
  - Alt is specified explicitly
  - For every Alt layer the Lat/Lon grid is the same
- Grid can be as dense as you have CPUs to handle
  - 4° × 4° global grid is routine
  - $\frac{1}{2}^{\circ} \times \frac{1}{2}^{\circ}$  regional grid is not too stressful
  - Vertical layers to geosynchronous altitude
  - → Representativeness errors are smaller from finer resolution
- Sophisticated error and correlation handling
  - Ingested correlations can vary seasonally, daily, etc.
  - Instrument errors as specified by data provider
  - Representativeness errors calculated from grid and instrument collection details



# Data Types Ingested

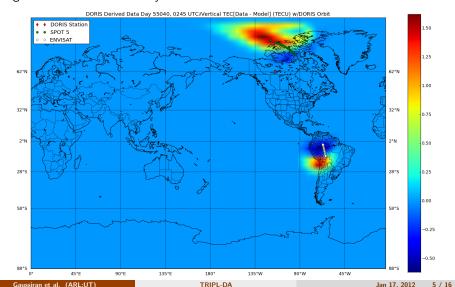
- Electron density
  - → In-situ measurements
  - $\rightarrow$  Ionosonde data  $(n_e(F_2), h(F_2))$
- Ray TEC
  - → Ground-based GPS/GNSS rays
  - → GPS/GNSS occultations
  - → LEO beacons (C/NOFS, RadCal, Transit (dead), ...)
  - → LEO DORIS rays NEW! (cf. GEOScan proposal)
  - → GPS/GNSS over-the-satellite rays





# Data Ingestion Example: DORIS LEO Data Results

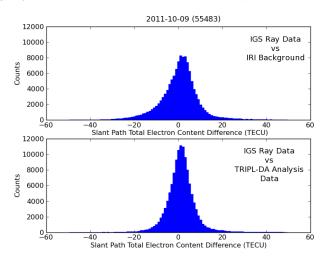
Example: DORIS data assimilated by TRIPL-DA: background model considerably modified



# Data Ingestion Example: GPS IGS Data Results

Trans-ionospheric ray data can markedly improve the bulk ionosphere specification.

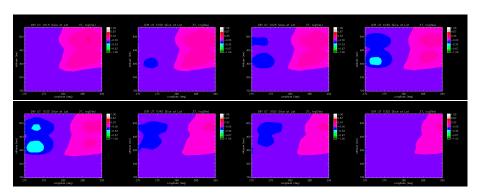
- Deviations after ingestion are more Gaussian.
- Skew and shape are significantly corrected, leaving only Gaussian uncertainties from instrument & representativeness errors.





# Ionosphere Dynamics - Example 1

TID observed over Wallops Island, 09 Oct 2006 – slice at 37N (5 min timesteps)



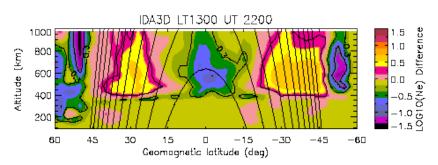
→ TRIPL-DA can capture small-scale dynamics on short time scales.



# Ionosphere Dynamics - Example 2

## Equatorial Fountain observation (Halloween Storm 2003)

→ TRIPL-DA can capture small-scale dynamics on short time scales.





## TRIPL-DA at CCMC

We have a small, internally funded, grant to install and test TRIPL-DA at the CCMC

- Research team has logins and some testing has been done
- Contingent on funding:
  - → Compile TRIPL-DA
  - → Run test suite and compare results
  - → Coordinate with CCMC staff to make TRIPL-DA available for ionospheric runs

# Ionospheric Research at ARL:UT

We continue to research a number of ionospheric topics at ARL:UT

- Improving the background model ingested into TRIPL-DA
- Ionospheric data errors
  - → Instrument thermal noise
  - → Ionospheric spatial correlation using GNSS data



# Background Models Ingested

TRIPL-DA is very successful at generating accurate TEC maps. But let's consider the background models used more carefully...

#### USU GAIM-GM

- $\rightarrow$  Very coarse, so is interpolated to finer grid ( $\sim 4\frac{2}{3}^{\circ} \times 15^{\circ}$  @ equator as currently available)
- → Limited in altitude (1400 km);
- $\rightarrow$  Limited in latitude (simply IFM poleward of  $\pm 67\frac{2}{3}^{\circ}$ )

#### • RIB-G

- → Frequently overestimates topside (by quite a bit)
- → Not updated in many years

#### IRI

- → Under current development by COSPAR/URSI
- → Limitied in altitude (2000 km)
- → Topside can be corrected

Model	Min. Alt. [km]	Max. Alt. [km]	Grid Size	Variances Present
GAIM	90	1400	$6^{\circ}  imes 15^{\circ}$	yes; IFM poleward of 662/3°
RIB-G	90	40000	user-specified	no
IRI	90	2000	user-specified	yes

► Compelling need for a new ensemble model for completeness!



## Ionospheric Data Errors

#### Starting Point:

Most ionospheric data sources have poorly-characterized errors.

→ This will come as a surprise to some users.

#### Error sources include:

- · Instrument (multiple sources; unique for each instrument type)
- · Registration how accurately an observation is stamped in space & time
- · Representativeness how well observational data matches the intentioned measurement
  - → spatial coverage/extent
  - → temporal coverage/extent
  - → spatial/temporal mixing

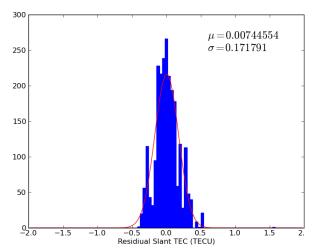
Many (not all) users consider only instrument errors!

▶ Our current study uncovers misunderstood GPS instrument errors.



## GPS Instrument Errors: Thermal Noise

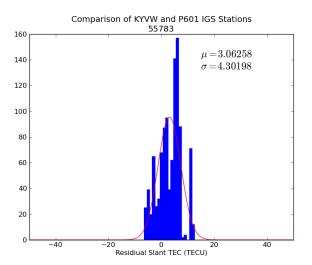
<u>Method:</u> 2 receivers, 1 antenna (common), relative diff. between two satellites, then relative diff. between two receivers: measures thermal noise





# GPS Instrument Error: Spatial Difference

Method: Residual slant TEC (relative rays) between two stations 10 km apart.





▶ This is MUCH larger than conventional wisdom.

# Summary

- ▶ TRIPL-DA is a significant evolution in ionosphere 3DVAR tools
  - · New data types greatly broaden capability
  - · Fine resolution enables study of detailed dynamics
  - · Captures magnetosphere as well
  - · Ensemble background model coming soon
- Capability to study detailed ionospheric dynamics demonstrated
  - · TIDs observed in action
  - · Equatorial fountain imaged temporally
- ▶ lonospheric science is data-poor need more sources!
  - · Note that many potential data sources aren't good enough (too-large errors)
  - · Current data sources are mostly regional and exclude oceans
  - · ARL:UT JHU/APL proposal to put DORIS Rx on Iridium-NEXT
- ▶ Ongoing study of iono. data source errors
  - · GPS thermal noise is much larger than assumed
  - · GPS ground data representativeness errors way underestimated
  - · Future work will examine representativeness in more detail



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