

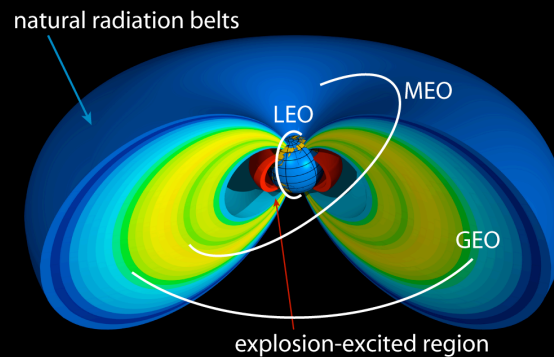
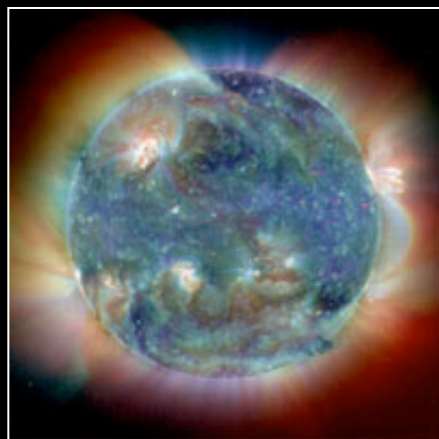


DREAM

The Dynamic Radiation Environment Assimilation Model

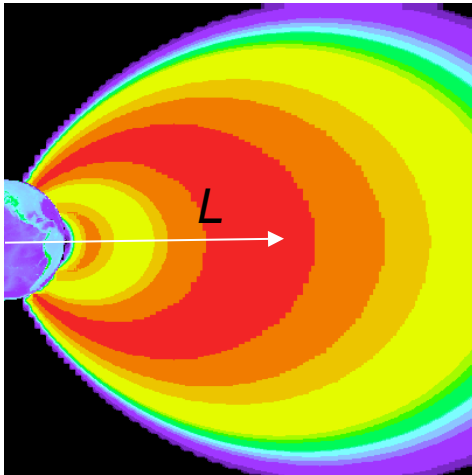
J. Koller

G.D. Reeves, R. L. Tokar, Y. Chen, M. G. Henderson, and R. H. W. Friedel

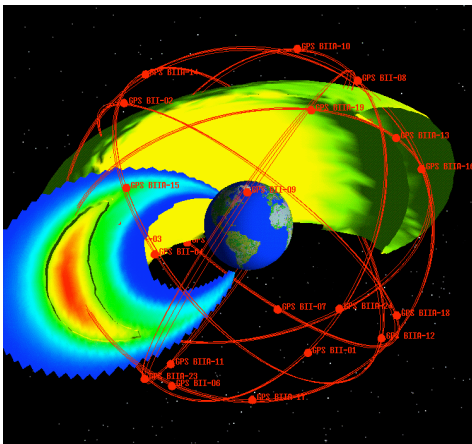


Radiation Belt Fluxes change dramatically but standard models are static or statistical

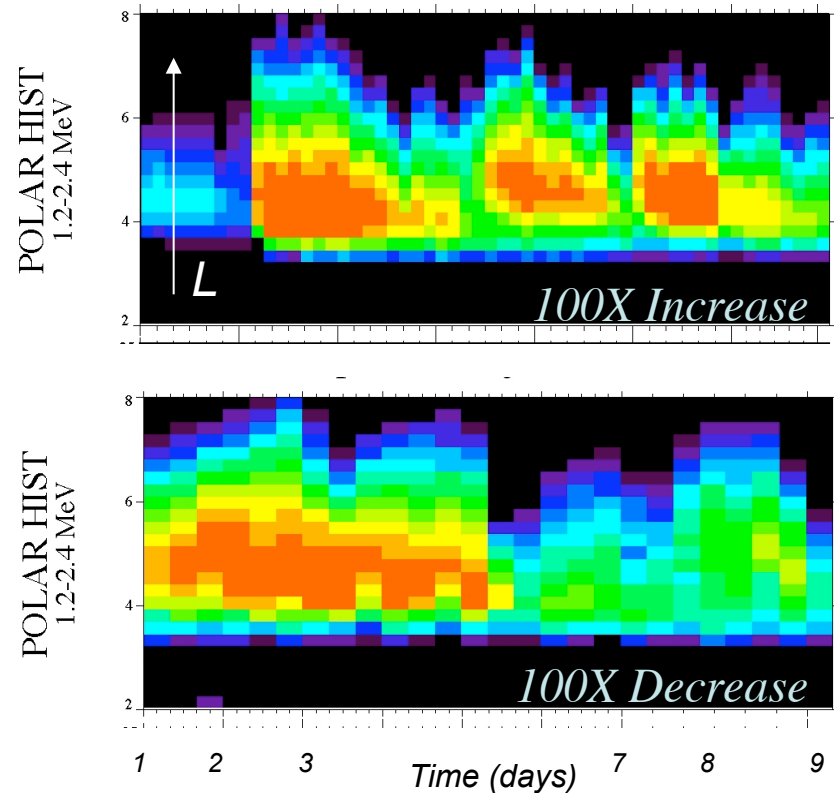
- AE8 - static



- CRRES - statistical

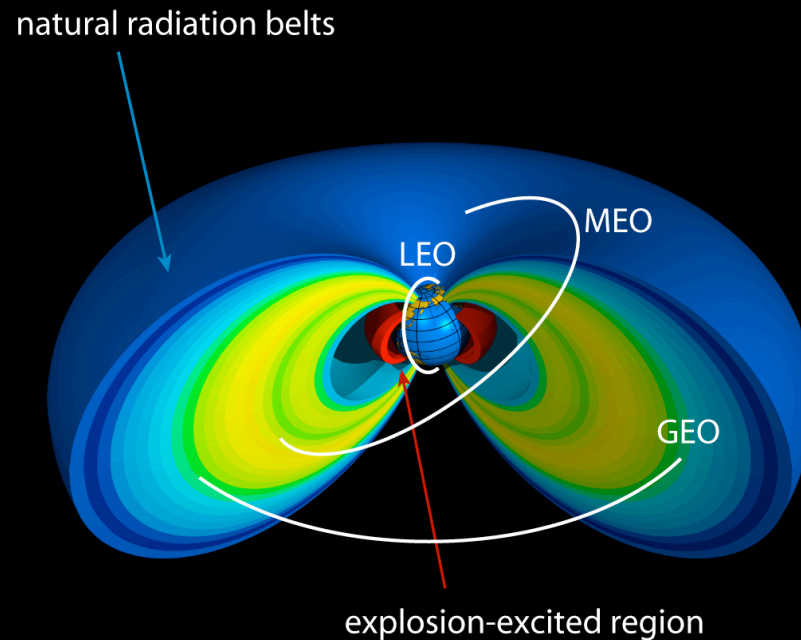


- Observations - dynamic



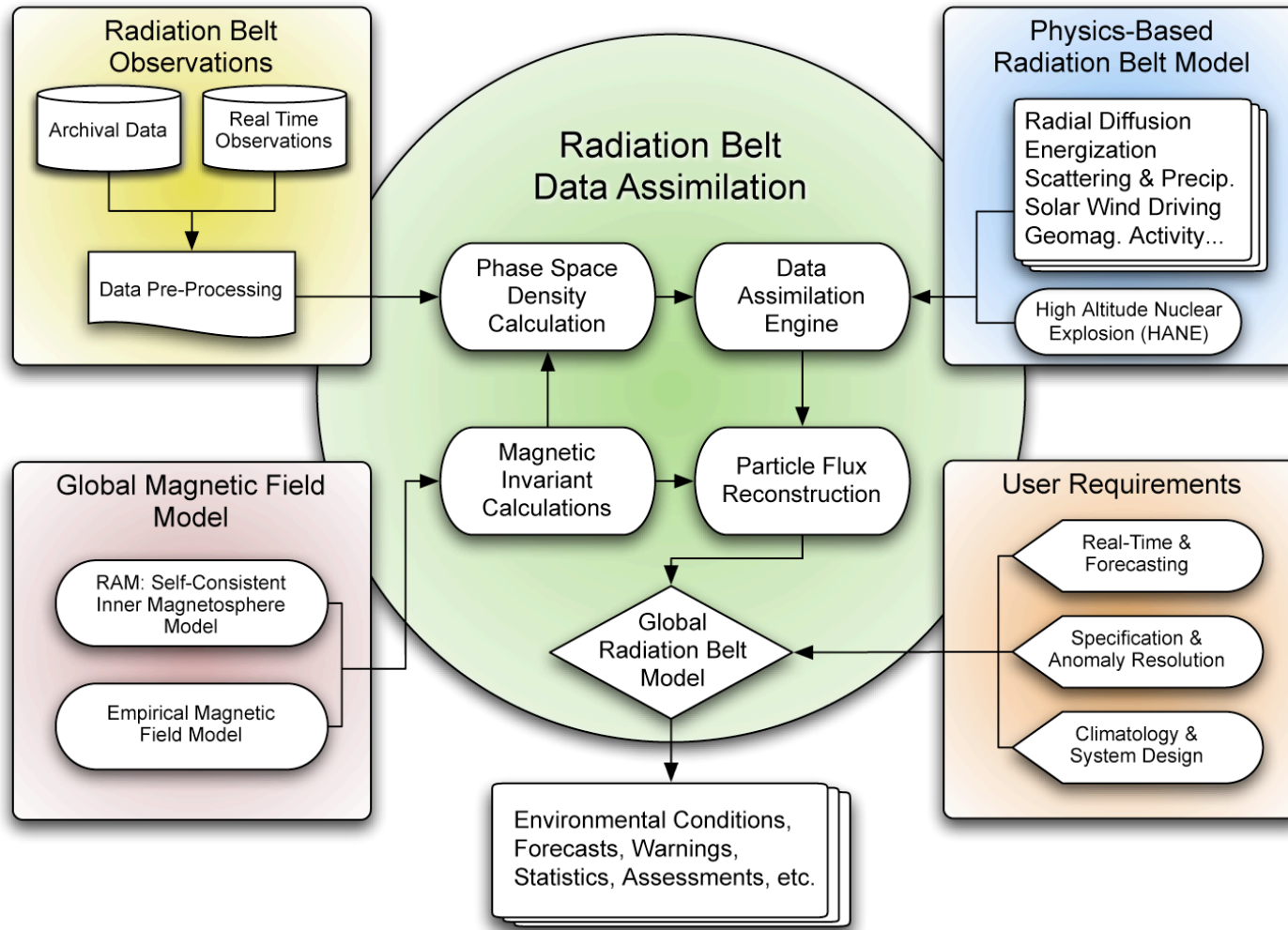
*Intensities change by up to 1000x
Different changes at different energies
Different changes at different locations*

DREAM: The Dynamic Radiation Environment Assimilation Model

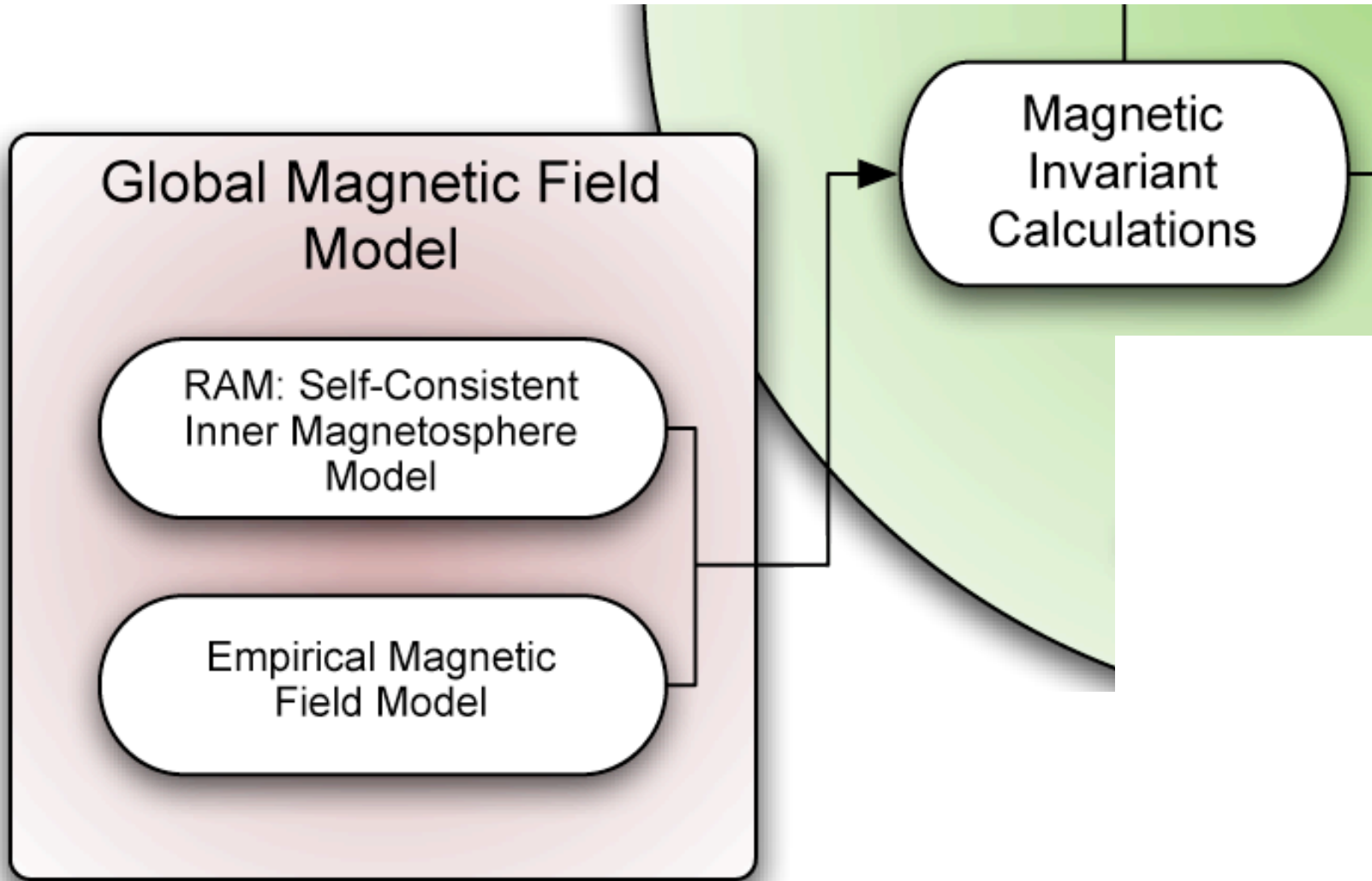


- Developed by LANL to quantify risks from natural and nuclear belts
- Uses Data Assimilation with GEO, GPS and other observations
- Couples ring current, magnetic field, and radiation belt models
- Goals: Specification, Prediction, Understanding

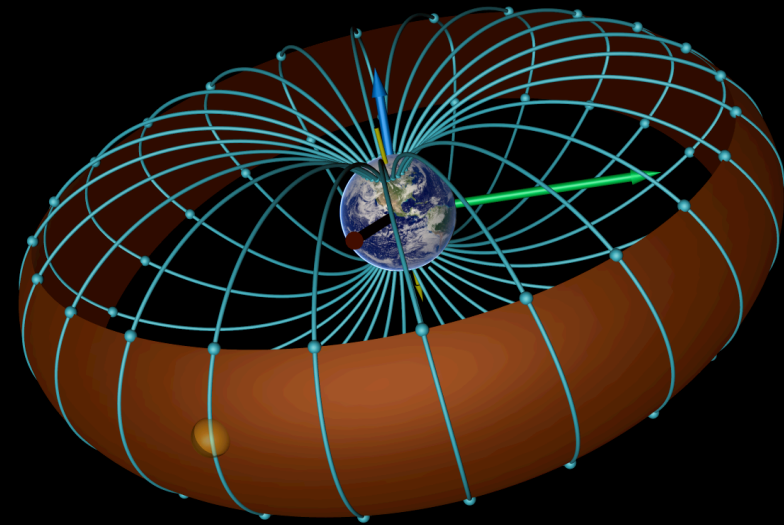
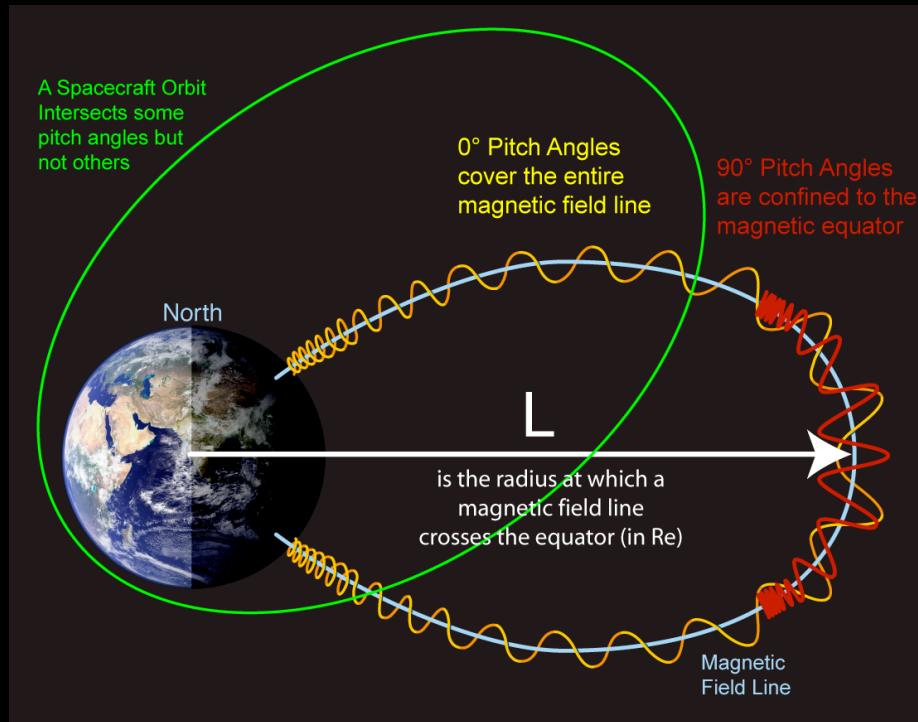
DREAM Computational Framework



DREAM Computational Framework



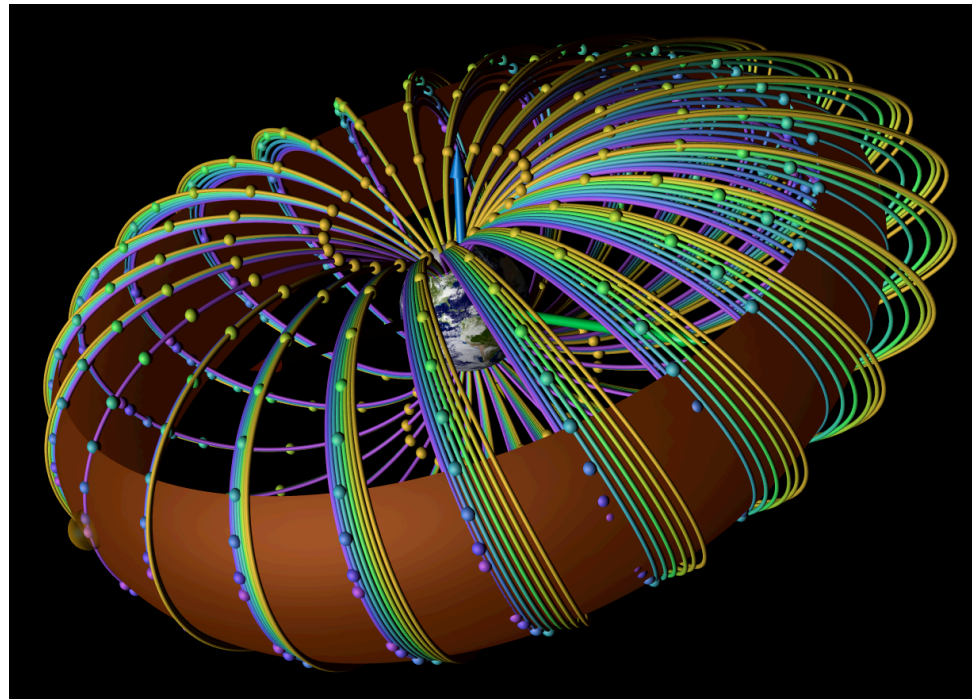
The magnetic field defines particle motion



- Fastest (ms): gyration around the magnetic field
- Medium (sec): bounce along the magnetic field between the magnetic mirror points
- Slowest (min-hr): drift around the Earth along a “drift shell” or “L-shell”

Accurately calculating the third adiabatic invariant (L^*) is a big part of DREAM

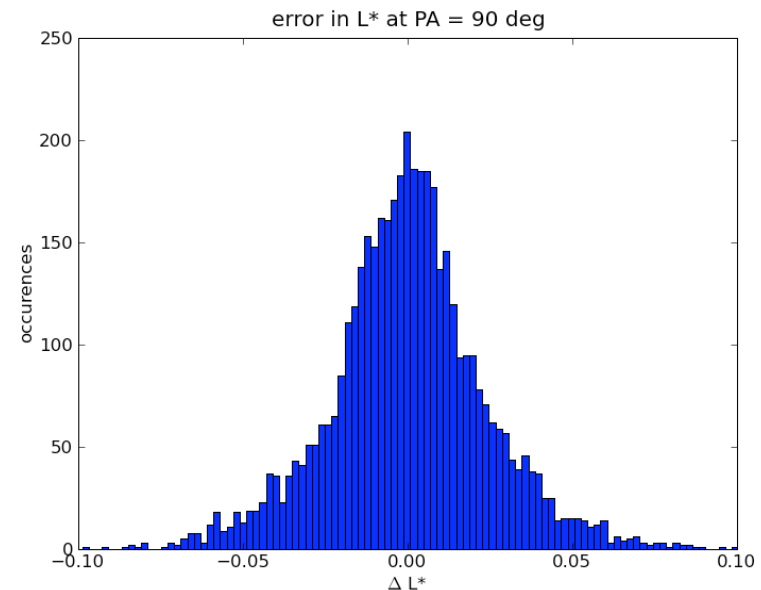
- In a dipole field L is independent of energy or pitch angle and is uniquely defined for a point in space
- In a real field L^* does depend on energy and pitch angle and L^* changes even for a fixed location



LANL* can calculate accurate drift shells six orders of magnitudes faster.

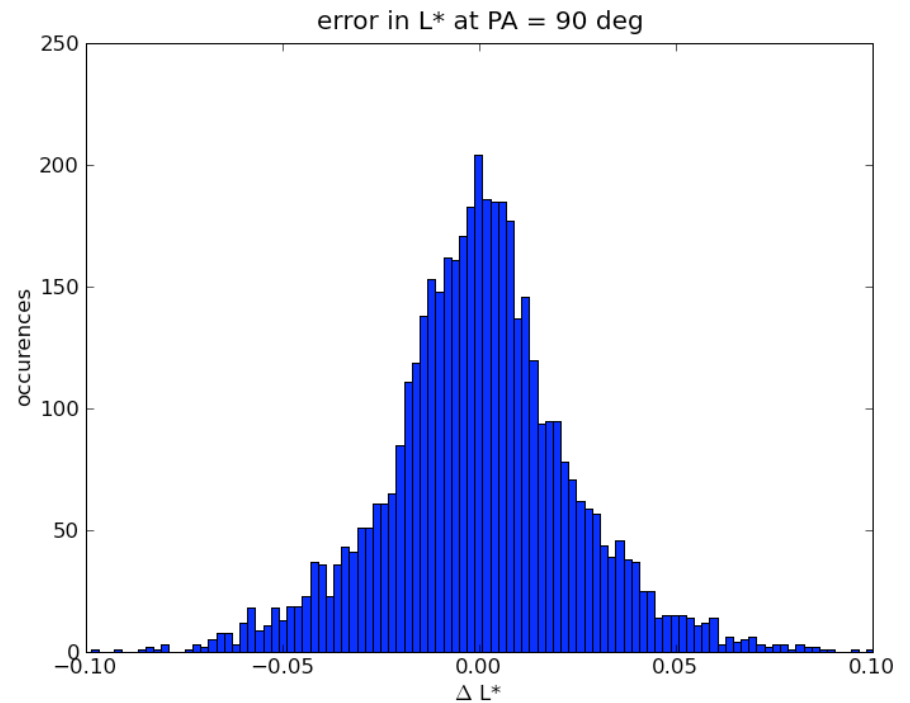
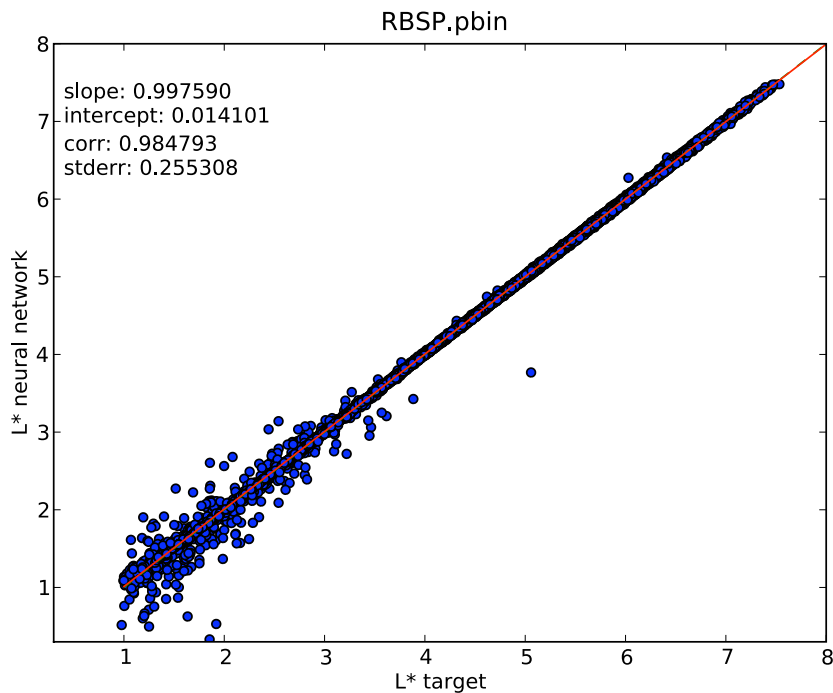
- based on a neural network technique replacing time-consuming drift shell integrations
- LANL* V2.0 based on Tsyganenko 2004 model
- trained on a whole solar cycle and larger spatial range $1.5 < Re < 10$
- error less than 2%
- Project website: <http://lanlstar.lanl.gov>

$$\mathbf{y} = \mathbf{f}^1 \left(\mathbf{W}^1 \mathbf{f}^0 \left(\mathbf{W}^0 \mathbf{x} + \mathbf{b}^0 \right) + \mathbf{b}^1 \right)$$

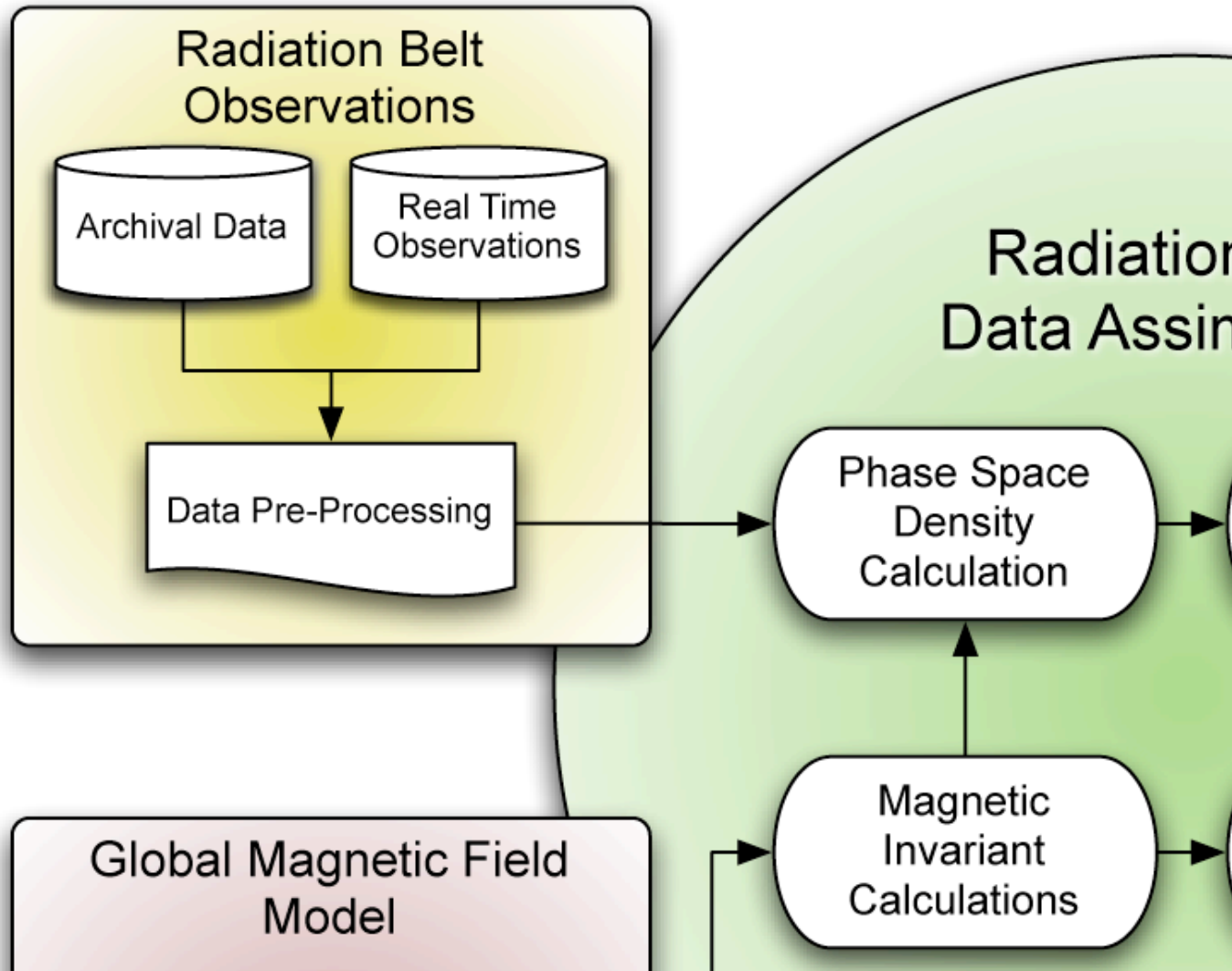


RBSP drift shells calculated in a few seconds for 5 min cadence

Model	time to calc. L* for RBSP
<i>Tsyganenko and Sitnov [2005]</i>	146 days
<i>LANL* V2</i>	12 secs



Observations + Magnetic Invariants => Phase Space Densities



Observations are in Flux

Physical equations use phase space density

Phase Space Density (PSD)

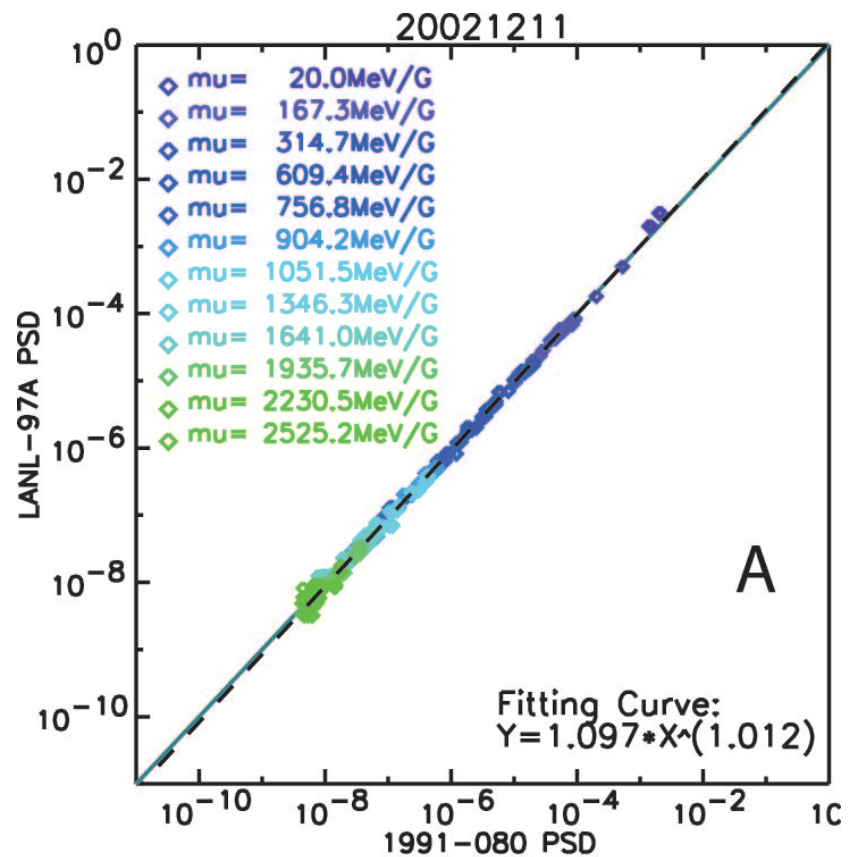
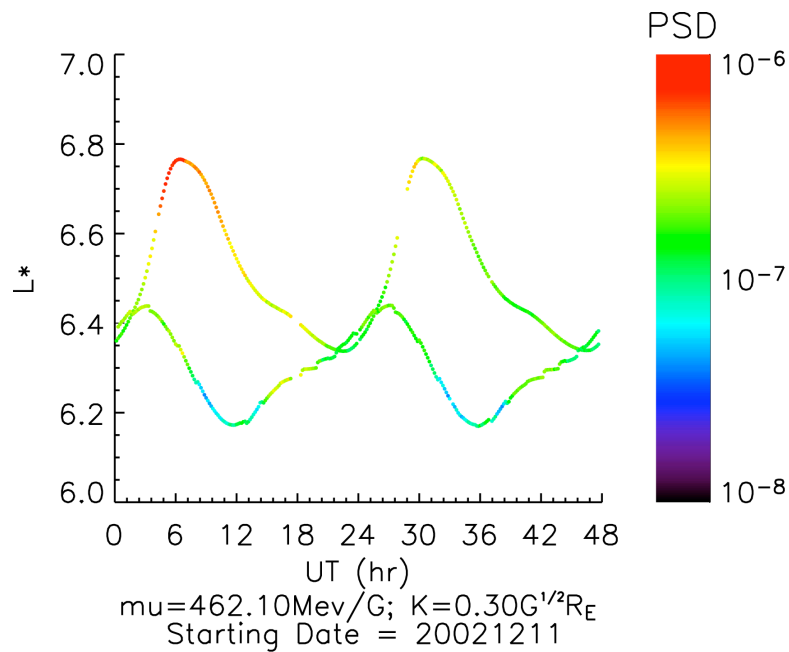
$$f = \frac{j}{p^2}$$

Equations of Motion
e.g. Radial Diffusion

$$\frac{\partial f}{\partial t} = L^2 \frac{\partial}{\partial L} \left(\frac{D_{LL}}{L^2} \frac{\partial f}{\partial L} \right)$$

- The conversion from flux (as a function of energy and location) to PSD (a function of magnetic invariants) is a critical step in radiation belt modeling
- This conversion must also be reversed at the end to get predictions in physically-relevant quantities (e.g. dose)

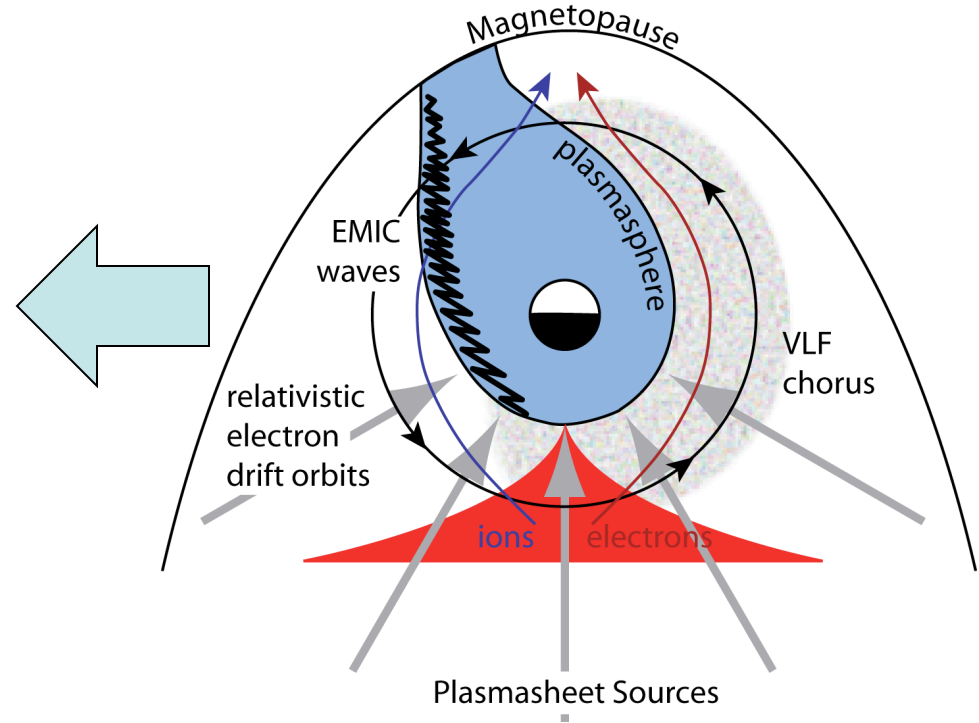
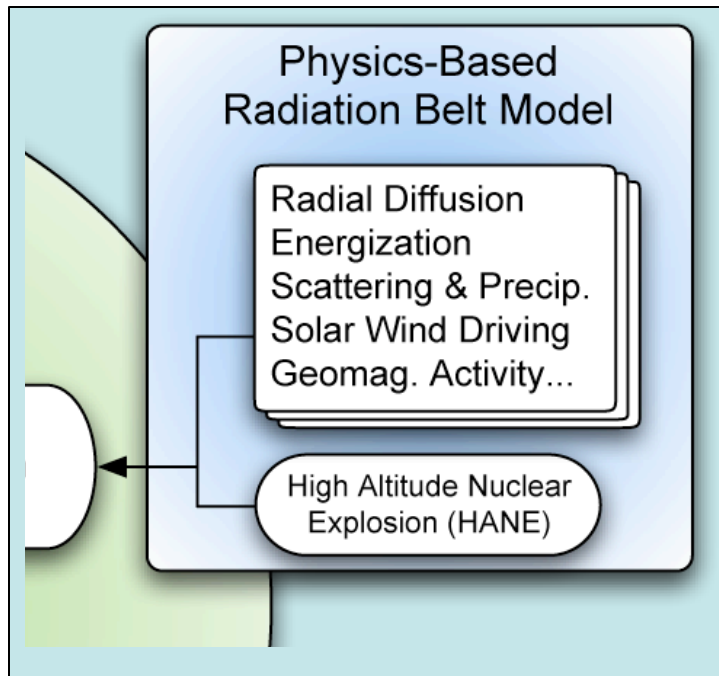
Pre-Processing data is a critical component. e.g. we also use PSD for calibration & validation



- “PSD Matching” tests both the intercalibration and the accuracy of the L^* calculation

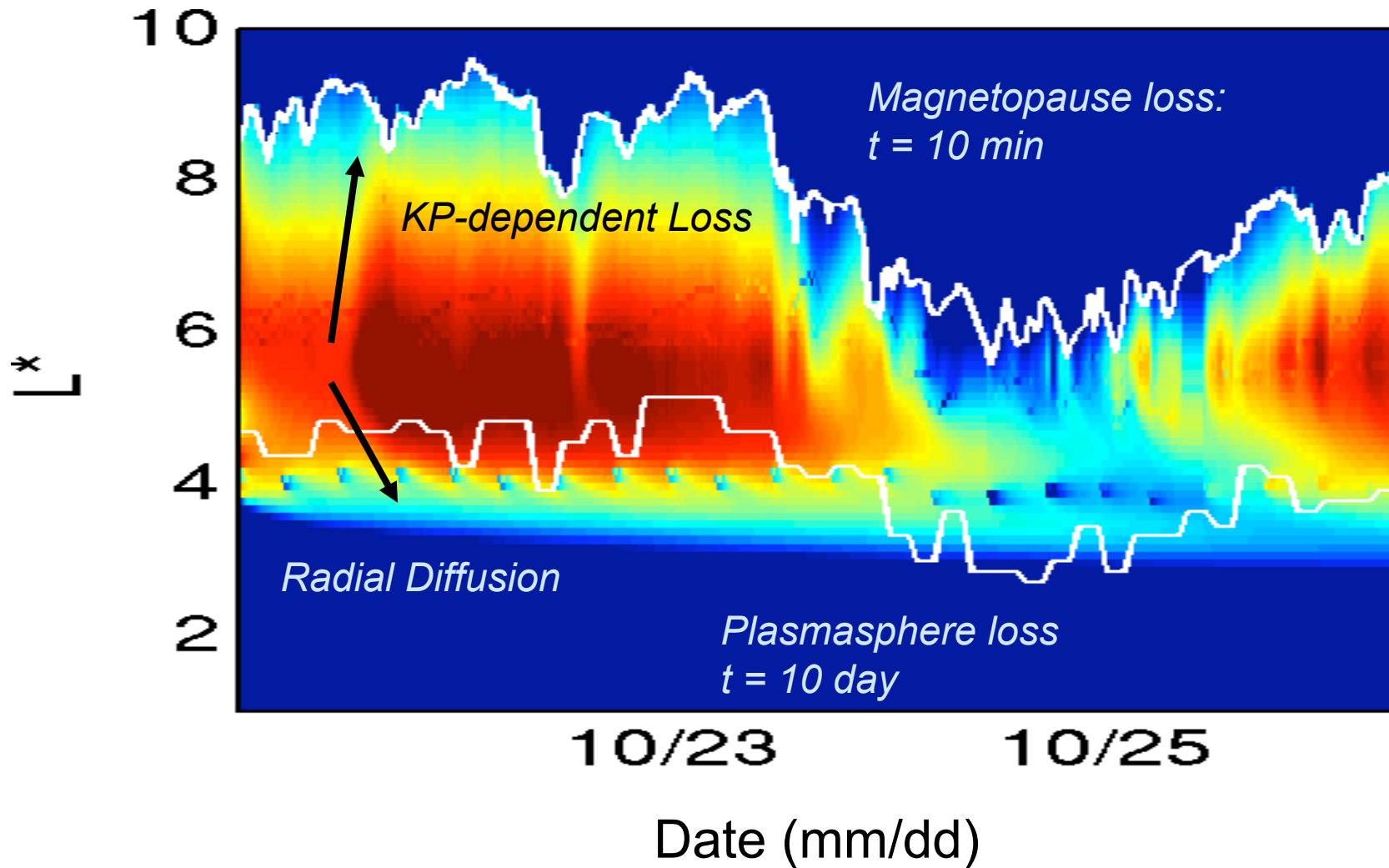
DREAM Computational Framework

Physics Models



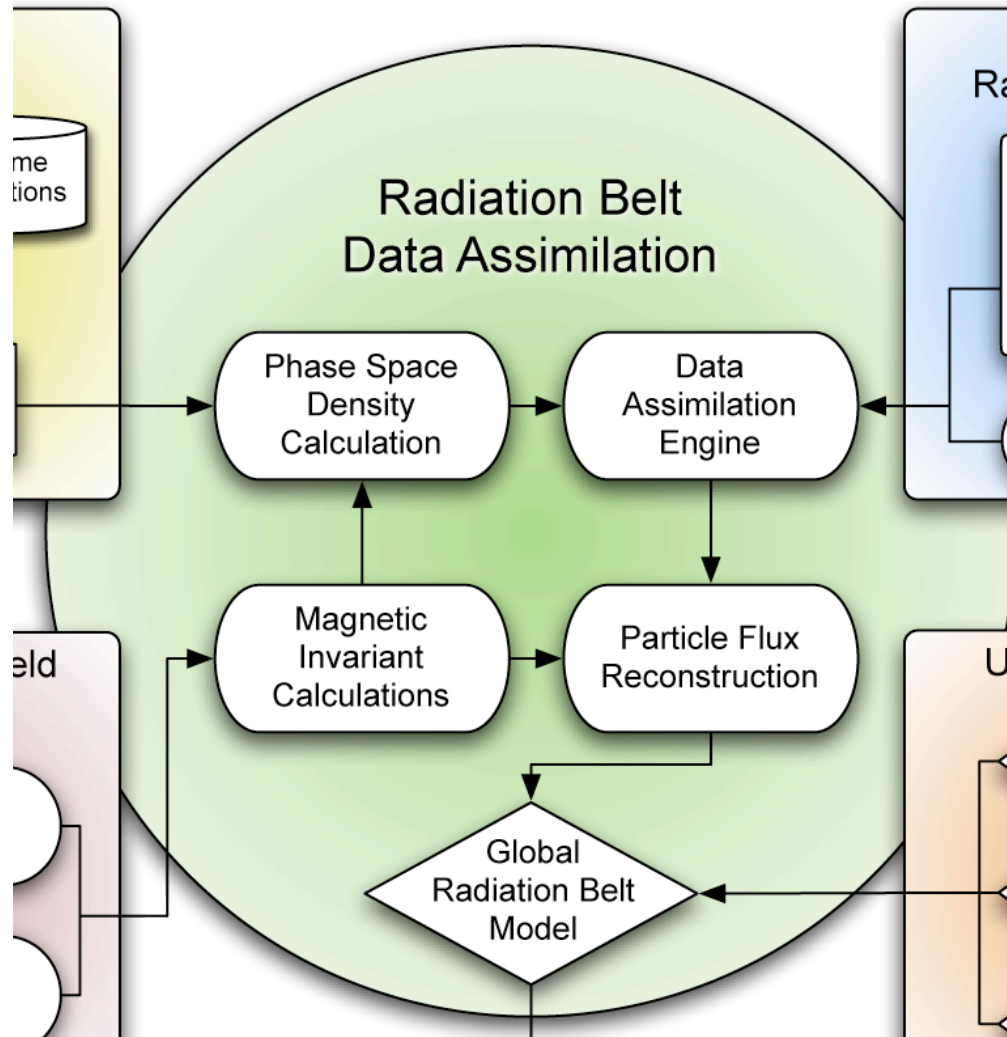
- DREAM can use physics models with various levels of physical and computational complexity
- But, physics models alone can not yet make accurate predictions

Phase Space Density as a function of L^* and Time



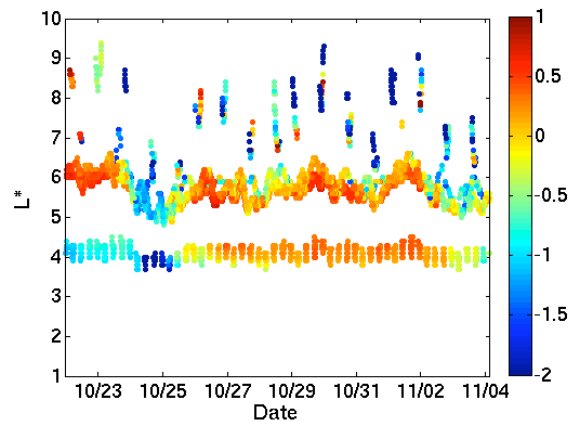
DREAM Computational Framework

Data Assimilation

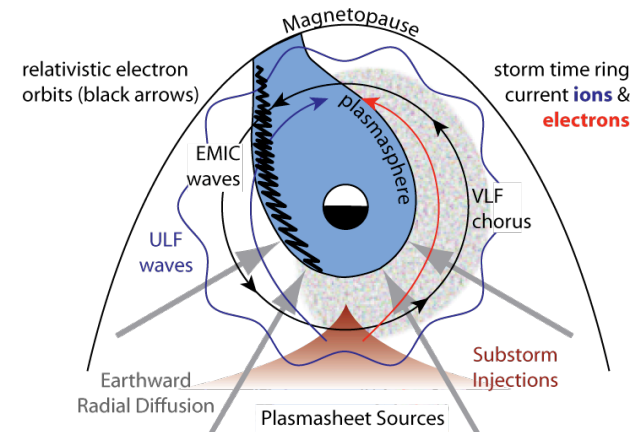


Data Assimilation turns sparse observations into global, data-driven solutions

Sparse and/or Heterogeneous Observations



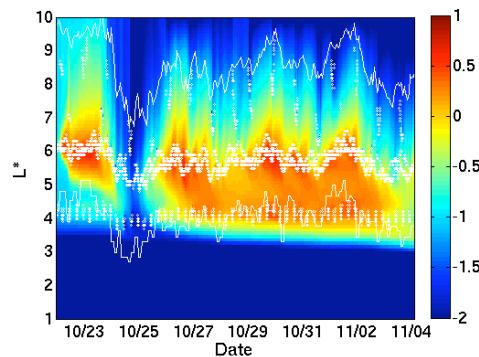
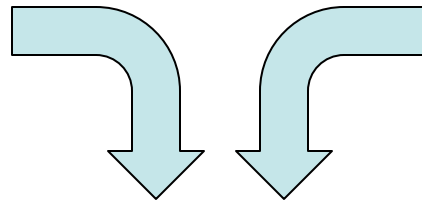
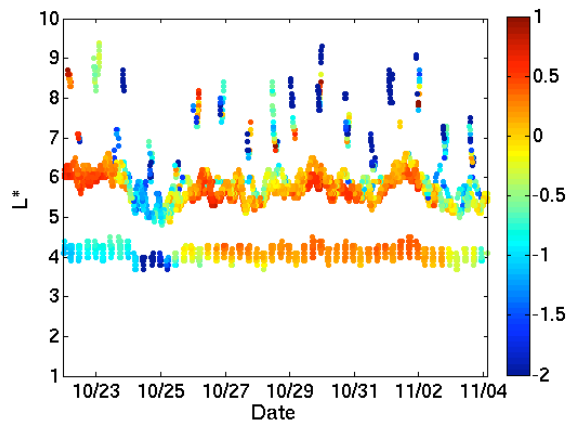
Complex Physical System



- Data Assimilation methods such as Kalman Filtering are techniques to combine physical models with sparse or conflicting data to produce optimized global solutions. The assimilation, or 'reanalysis', gives information not present in the model or measurements alone

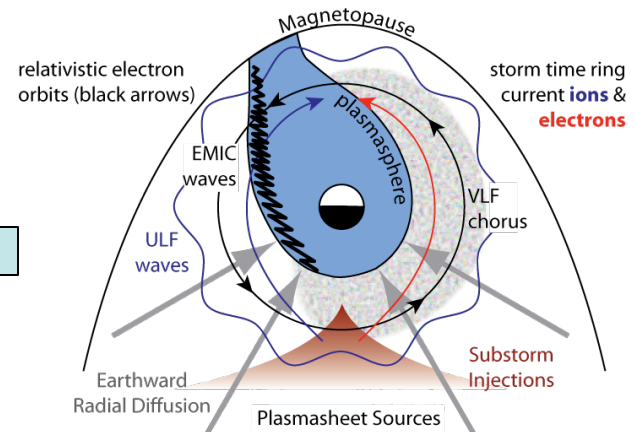
Data Assimilation turns sparse observations into global, data-driven solutions

Sparse and/or Heterogeneous Observations



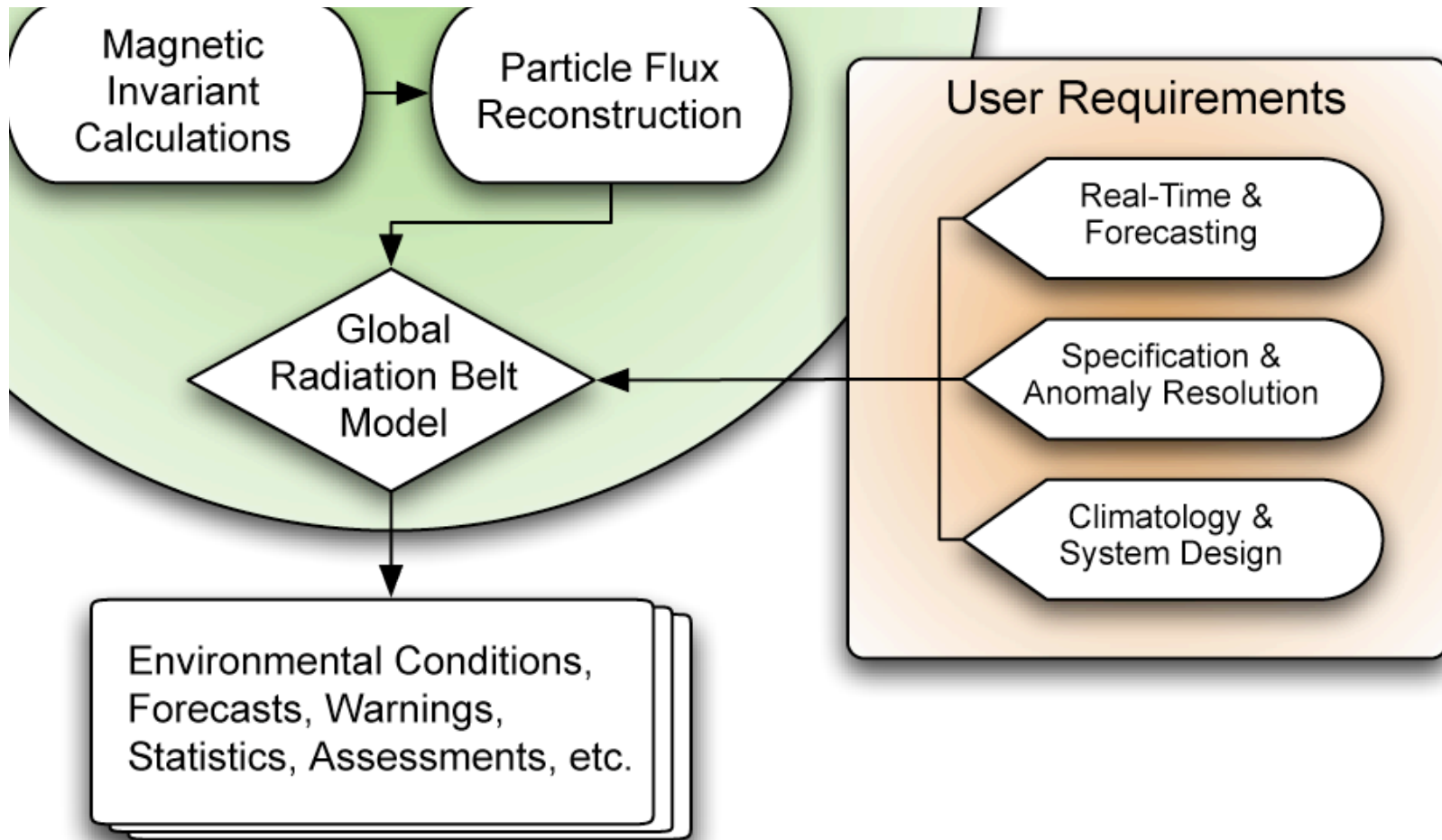
Global, Real-Time Data-Driven Solution

Complex Physical System



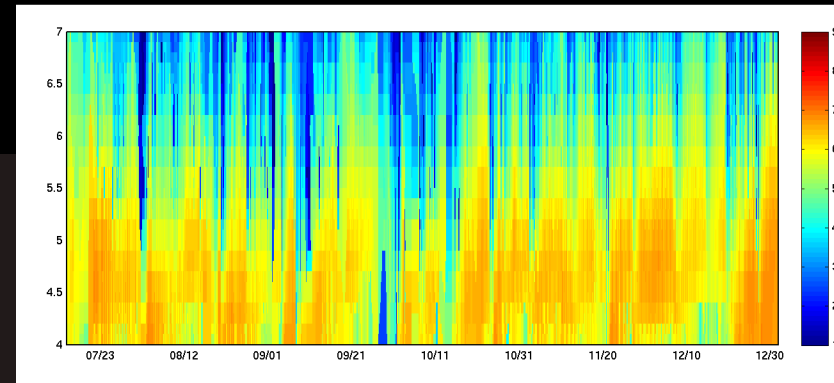
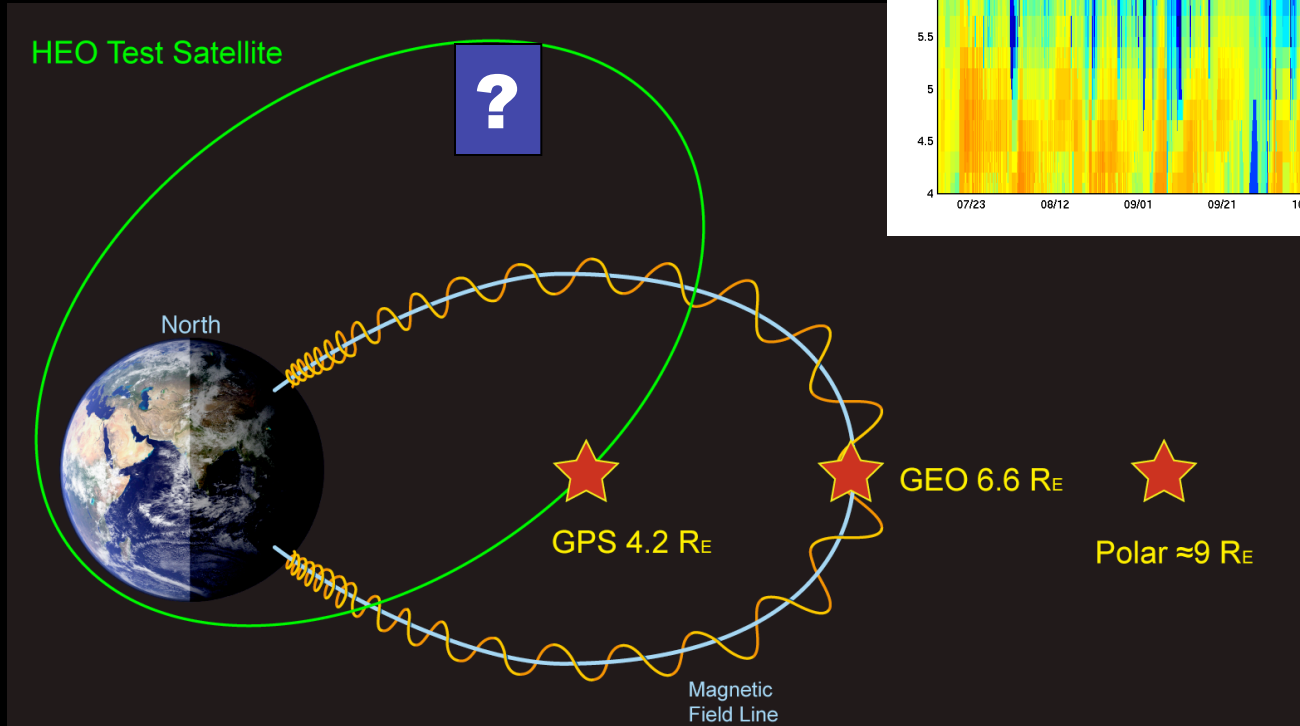
DREAM Computational Framework

Validation and Applications



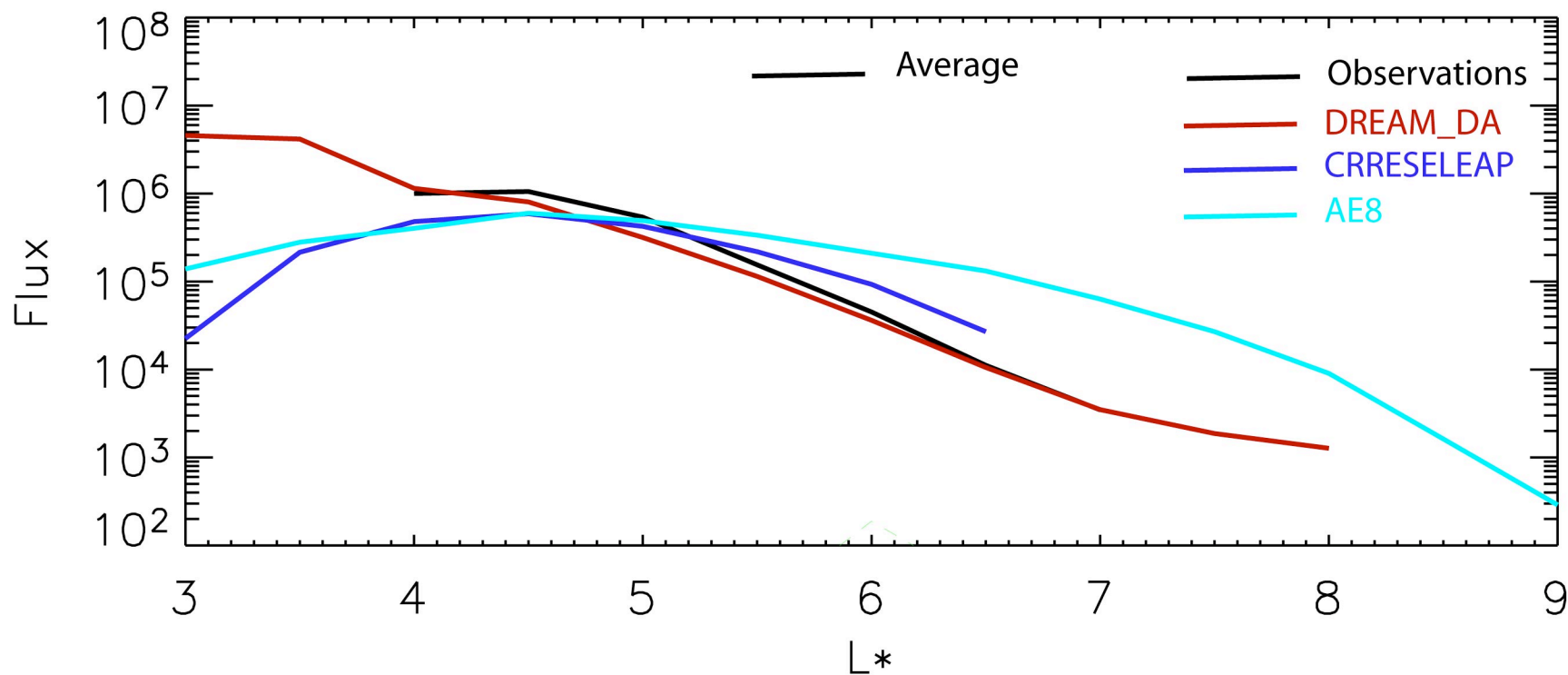
Prediction of flux in different satellite orbits

~ 1 MeV electron flux at HEO-3

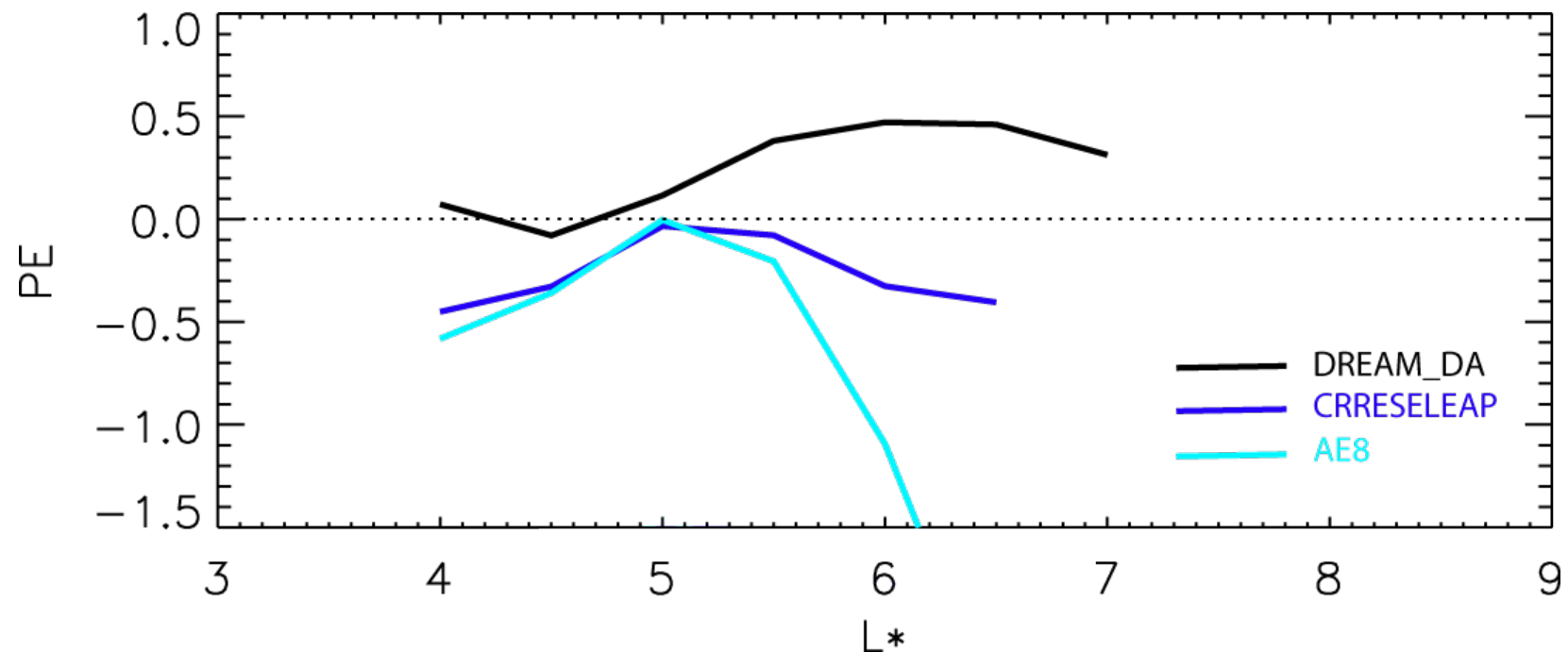


HEO is a different orbit and is not used as input to DREAM

Validation 1: Average Flux vs Altitude



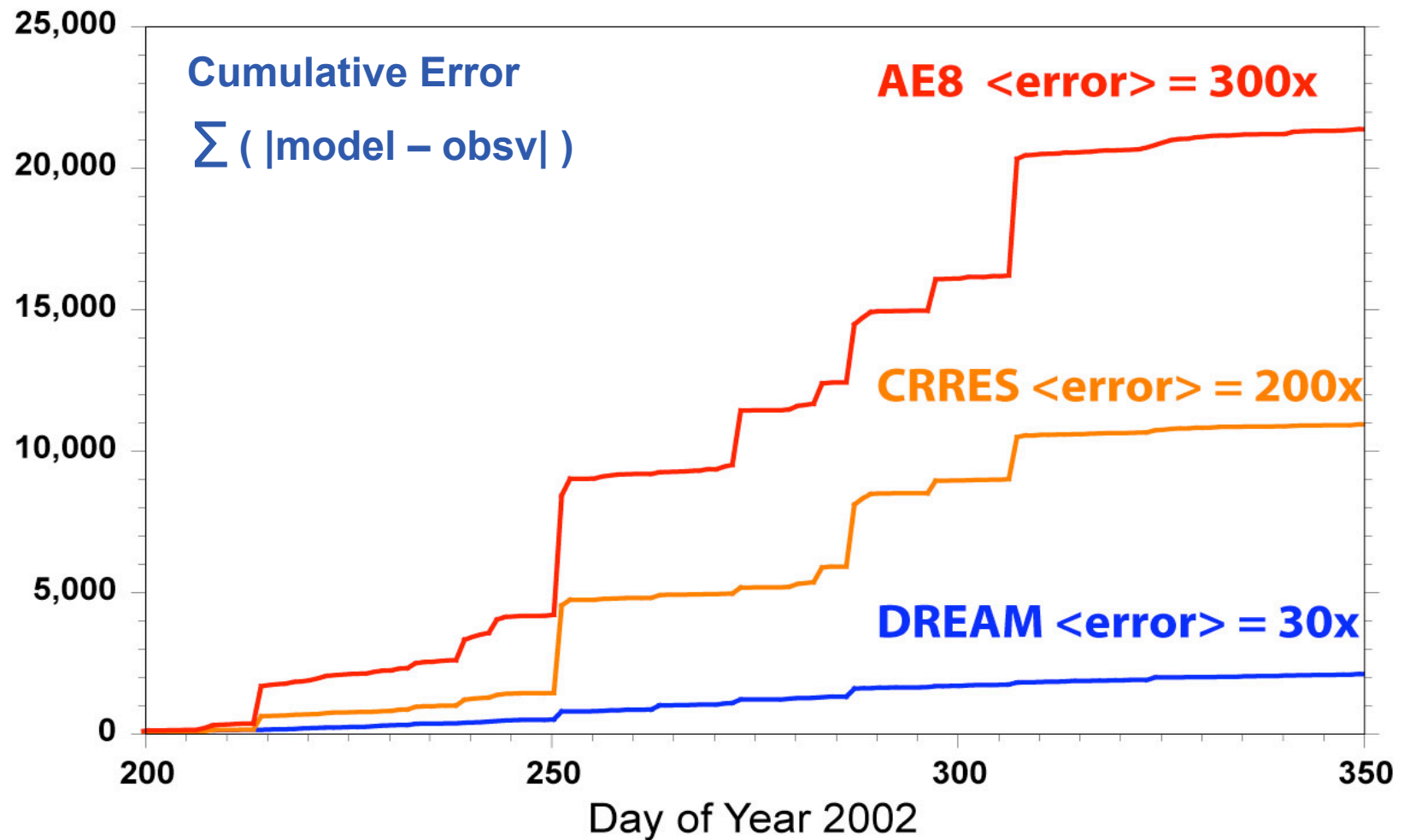
Validation 2: Prediction Efficiency testing variation around the mean



$$PE = 1 - \frac{\sum (\text{model} - \text{obsv})^2}{\sum (\text{obsv} - \langle \text{obsv} \rangle)^2}$$

Validation 3: Average absolute error

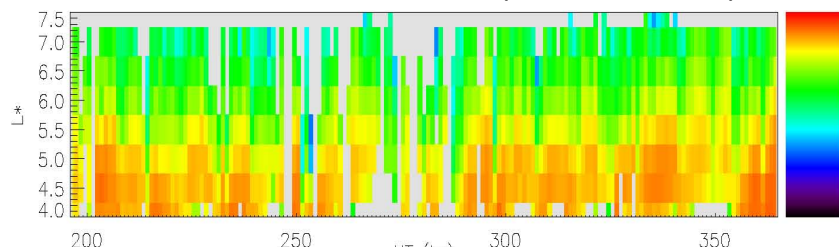
DREAM gives ~10x improvement



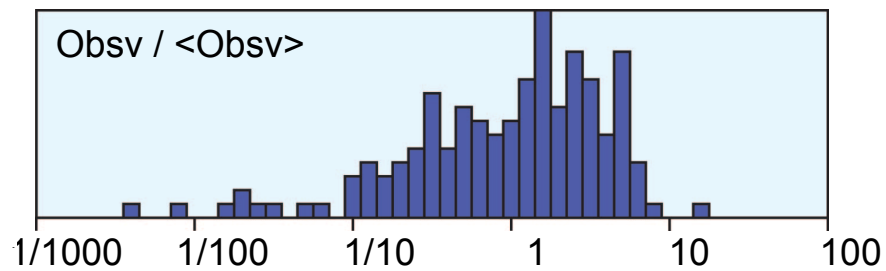
Flux vs L^* , Time (1 MeV)

Distribution at $L^*=6$

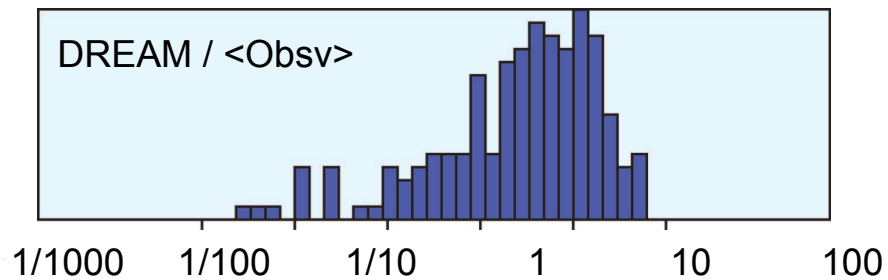
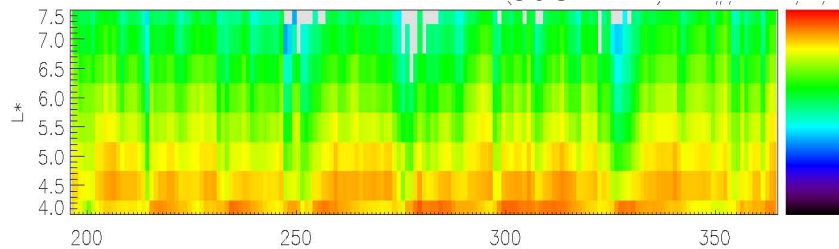
HEO Observations (validation set)



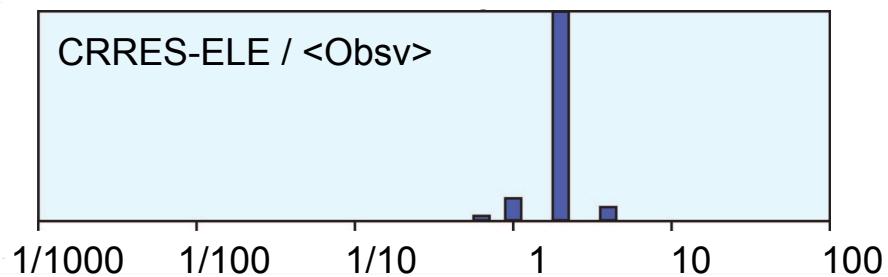
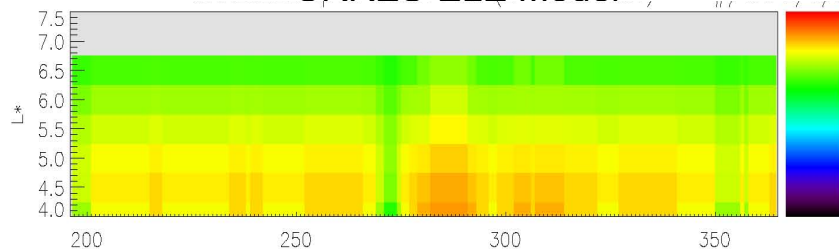
Variation around the Mean Observations



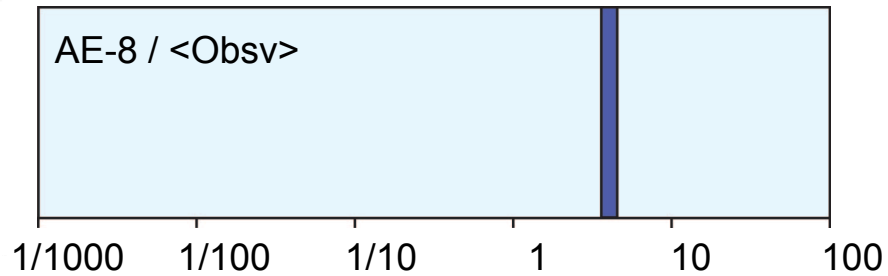
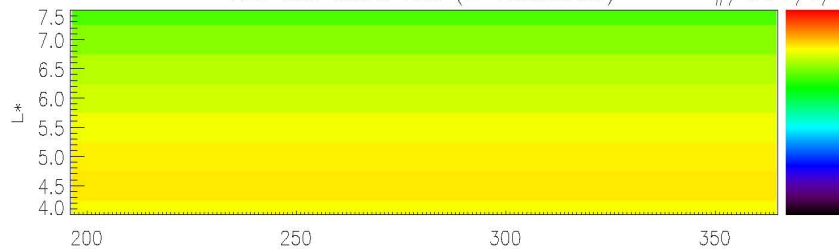
DREAM Model



CRRES-ELE Model

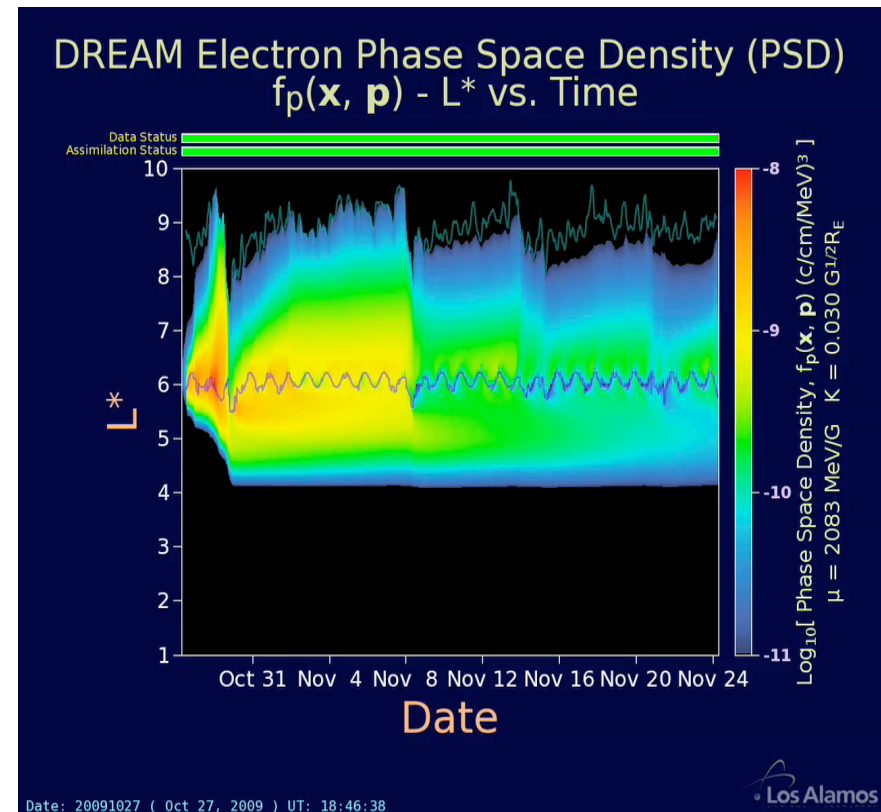


AE-8 Model

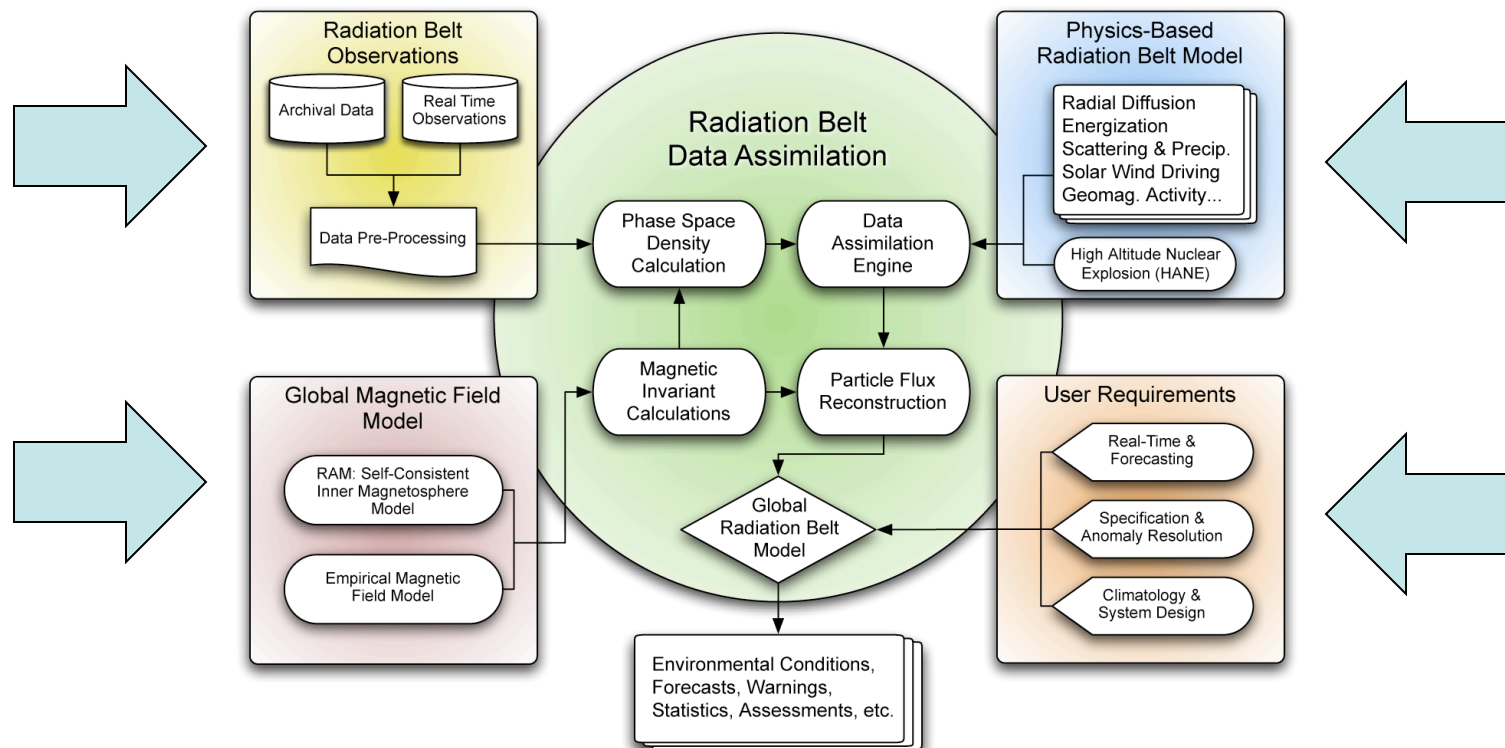


DREAM – Research to Operations (R2O)

- Alpha version recently installed for testing at AFRL R2O center in Albuquerque: SWFL
- Real-time single GOES satellite input
- It's platform independent and will run on a desktop computer
- A demo mode runs with time speeded up
- The same tool allows users to look back at archived assimilations
- Forecasts can be produced using the nowcast + a physics model

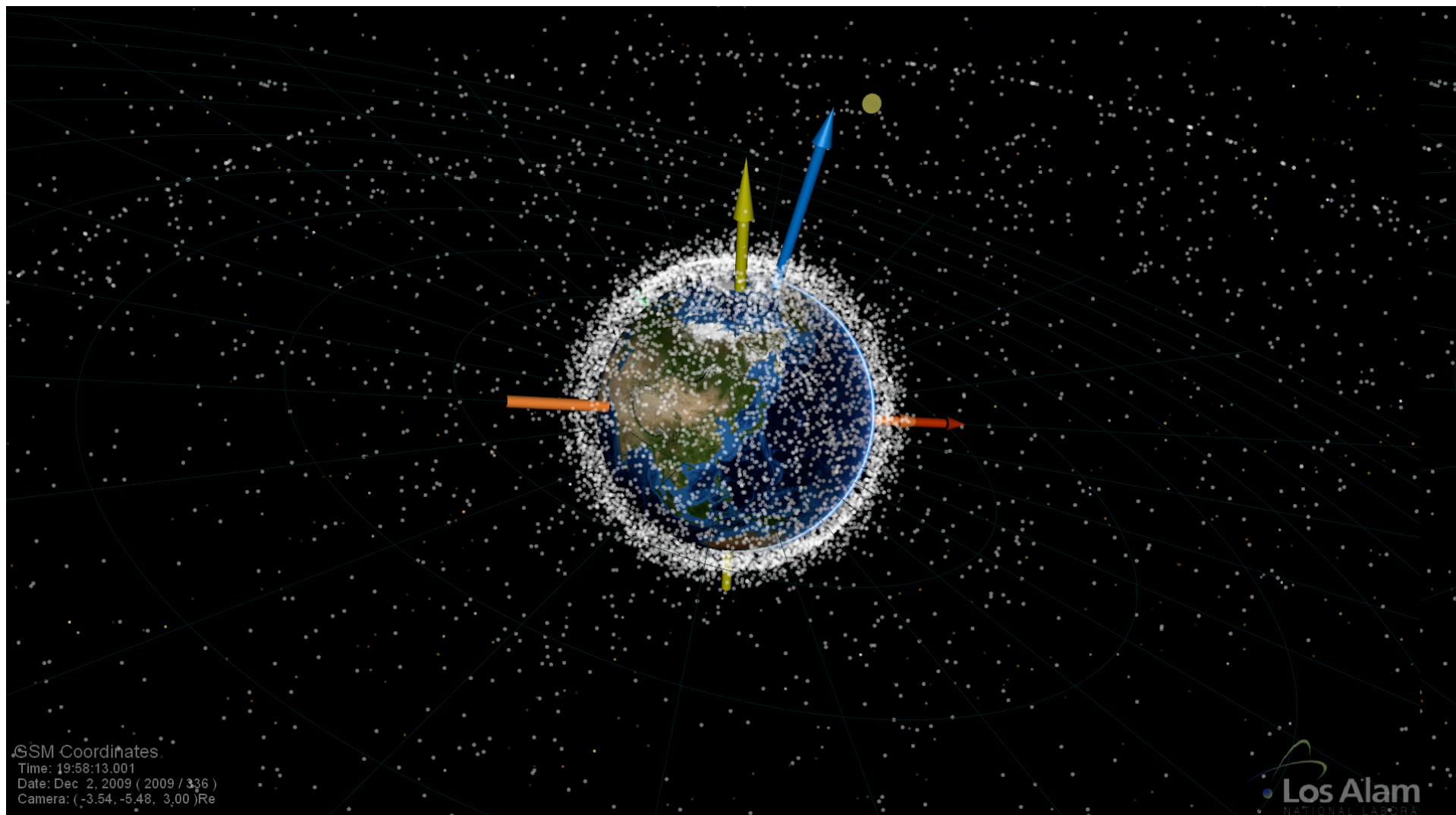


New and Future work



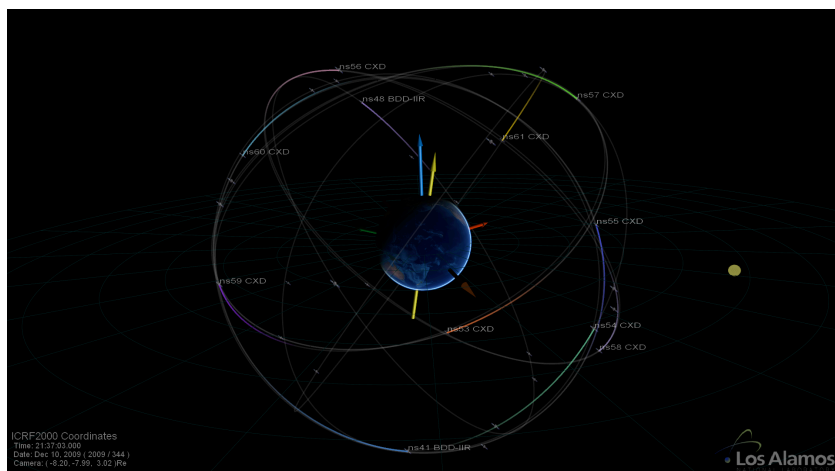
We are currently working on next-generation capabilities in all of the major components of DREAM

Client for Service Oriented Architecture for SSA applications



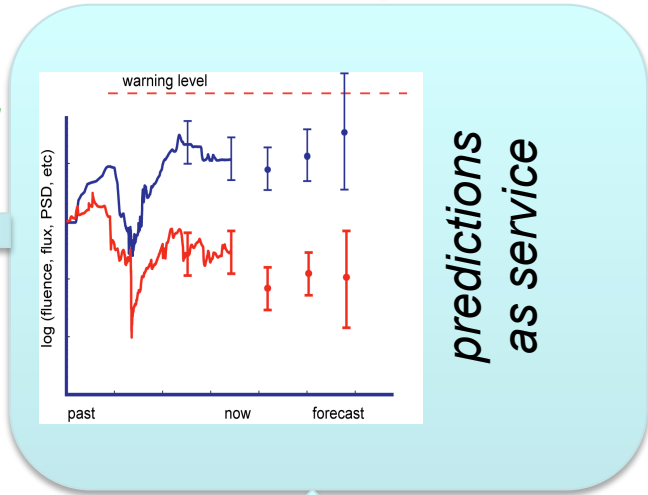
Space Environment SOA

User Interface/Client
LANL 3D
Visualization Tool



Nominal

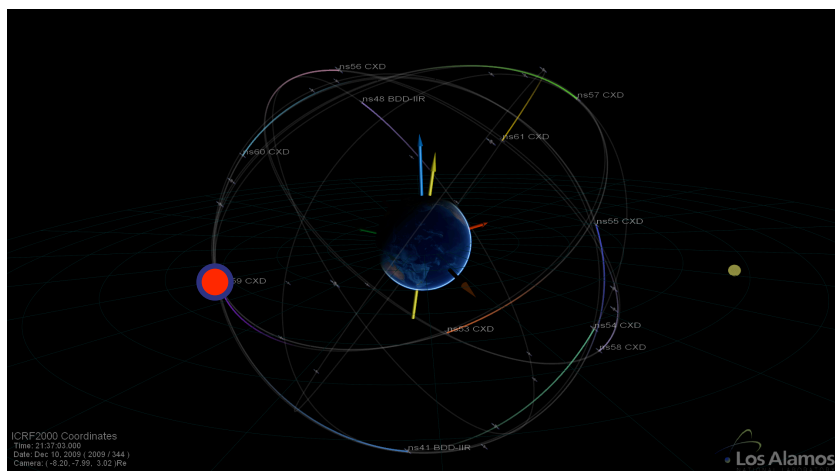
Data Service



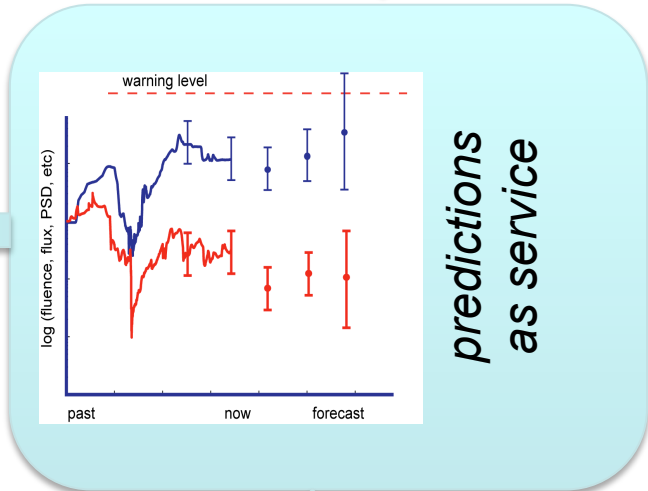
Spacecraft Orbits

Space Environment SOA

User Interface/Client
LANL 3D
Visualization Tool

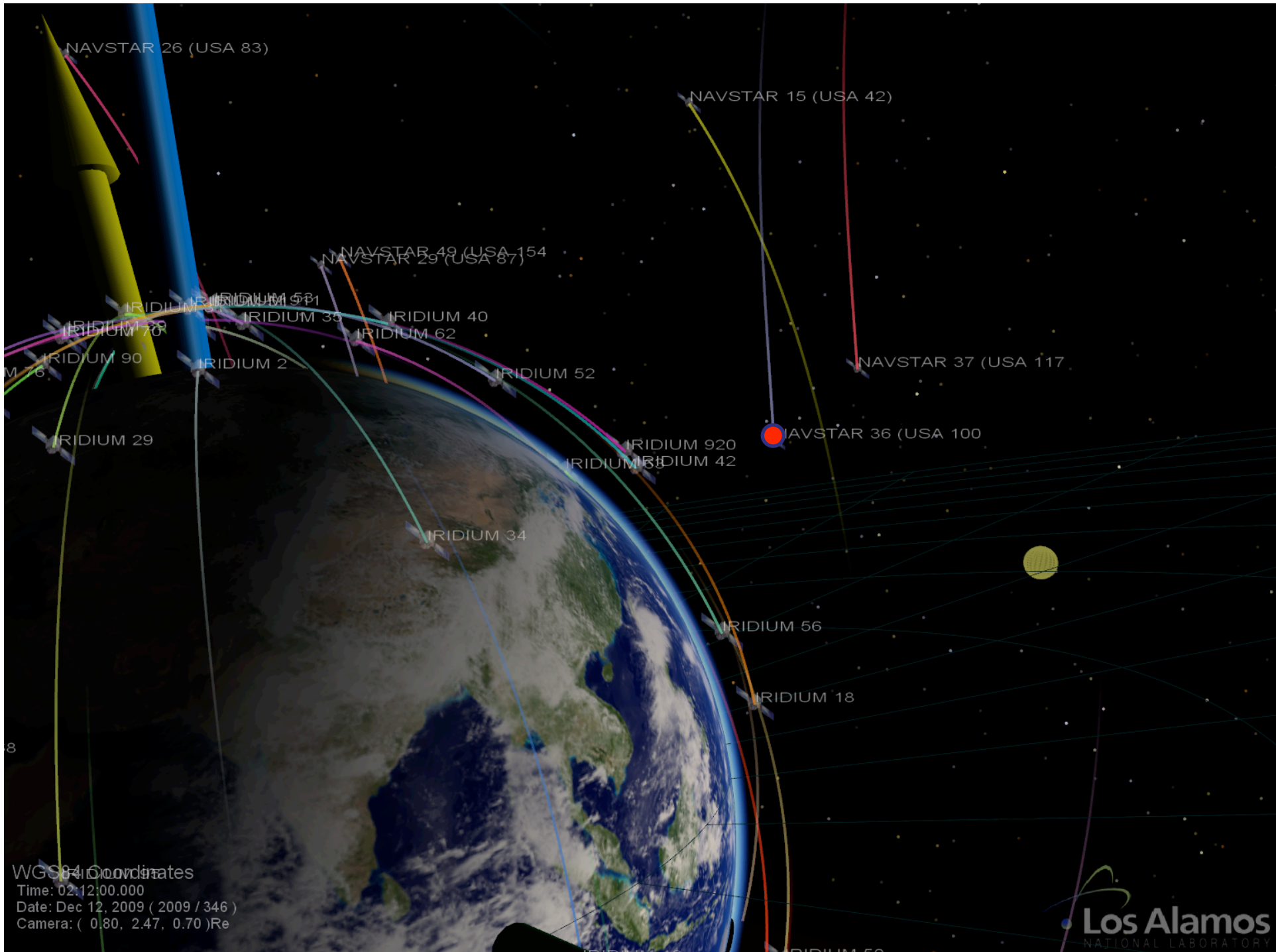


Data Service



Extreme

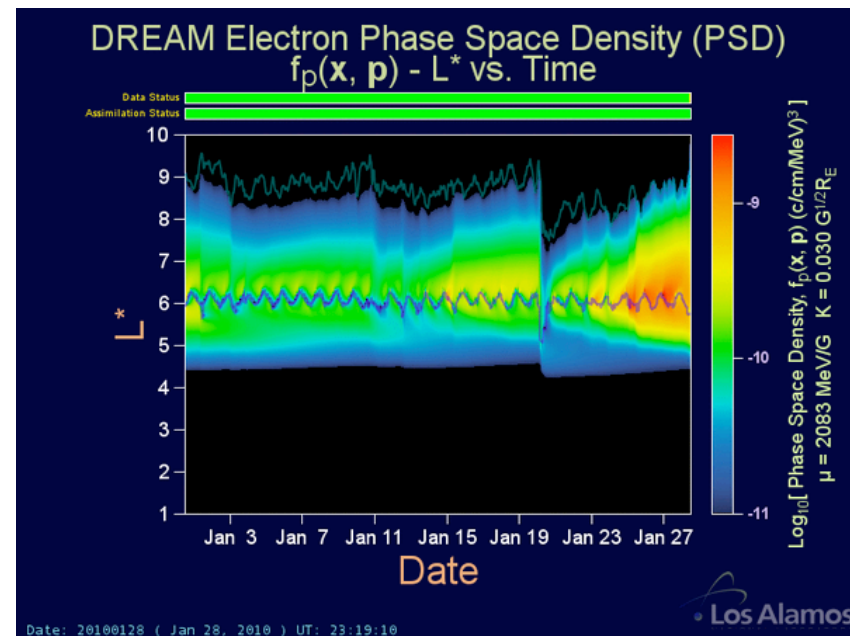
Spacecraft Orbits



Other projects feeding into DREAM

- Spacepy: a library written in Python, C, C++, F90 including
 - CDF support
 - LANL*
 - RB modeling
 - V&V algorithms
 - Data Assimilation
 - + Launch at GEM 2010
 - + <http://spacepy.lanl.gov>
- DREAM website with real-time nowcast:

<http://dream.lanl.gov>



igoogle app

iGoogle

http://www.google.com/ig?hl=en&referrer=ign

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- DREAM Output

Updates

- Friends

Chat

Search, add, or invite

Done

DREAM Output

DREAM Electron Phase Space Density (PSD)
 $f_p(x, p) - L^*$ vs. Time

DREAM project alpha stage visualization output

Want to make your own gadget? [Get started.](#)

Google Calendar

January 2010

S	M	T	W	T	F	S
27	28	29	30	31	1	2
3	4	5	6	7	8	9
10	11	12	13	14	15	16
17	18	19	20	21	22	23
24	25	26	27	28	29	30
31	1	2	3	4	5	6

Showing events until 2/28. [Look for more](#)

Weather

Los Alamos, NM

32°F Current: Snow Showers
Wind: N at 6 mph
Humidity: 100%

Thu 37° | 24° Fri 35° | 22° Sat 38° | 25° Sun 40° | 26°

Movies: 87544

[The Book of Eli](#) Trailer - IMDb
★★★★☆ 28 reviews
[Regal Santa Fe Stadium 14](#) - 5:00 7:50 [More](#)

[The Tooth Fairy](#) Trailer - IMDb
★★★★☆ 12 reviews
[Storyteller Dreamcatcher 10](#) - 7:05 9:25pm [More](#)

Other on-going and future work

- Full integration of RAM-SCB, DREAM assimilation, and global MHD models
- Extending the methods that we've demonstrated to other parts of the space environment such as the surface charging environment and global electric field
- New physics models for acceleration, scattering, and loss
- Development of AE9 and a standard solar-cycle model as a baseline for forecasts and satellite design
 - Ongoing LANL/AFRL/NRO/Aerospace collaboration
- Visualization tools for SSA demonstrations